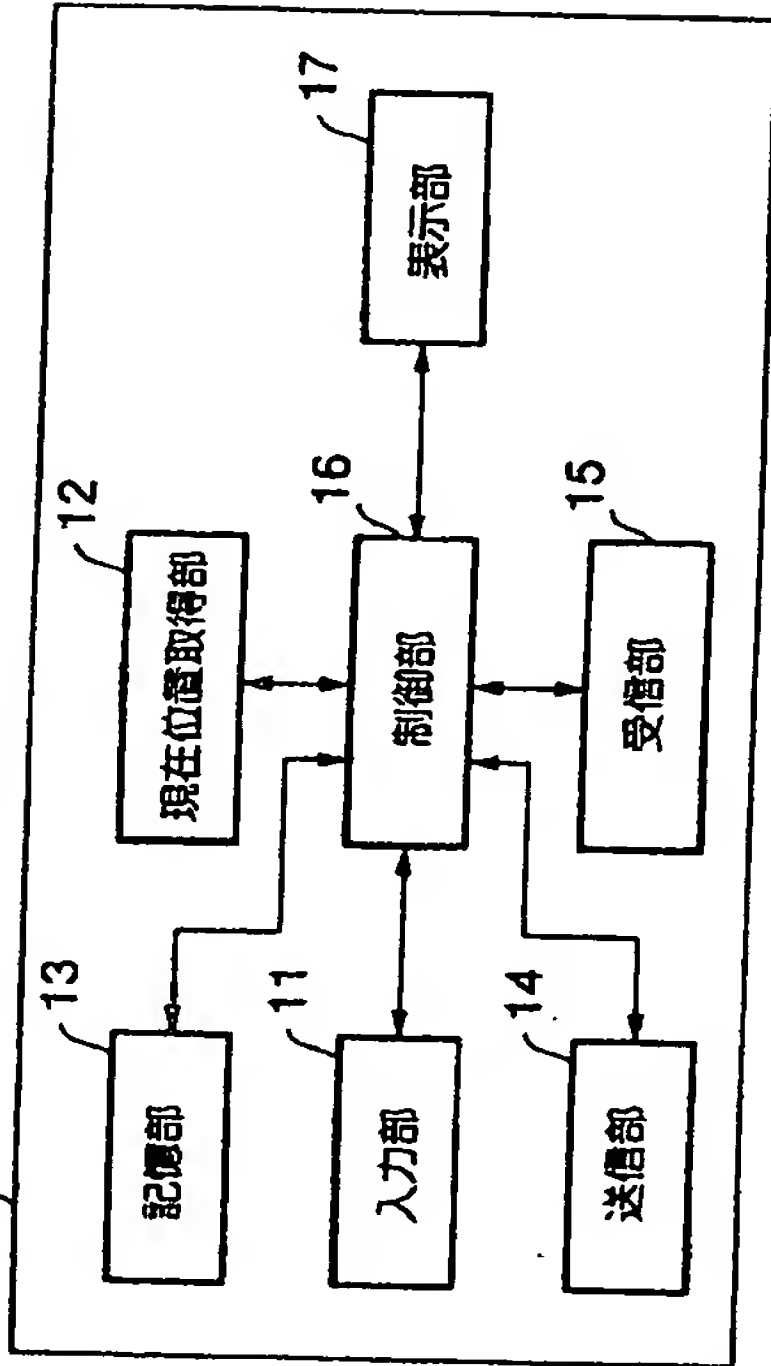


[図1]

A 自車側ナビゲーション装置



B 他車側ナビゲーション装置

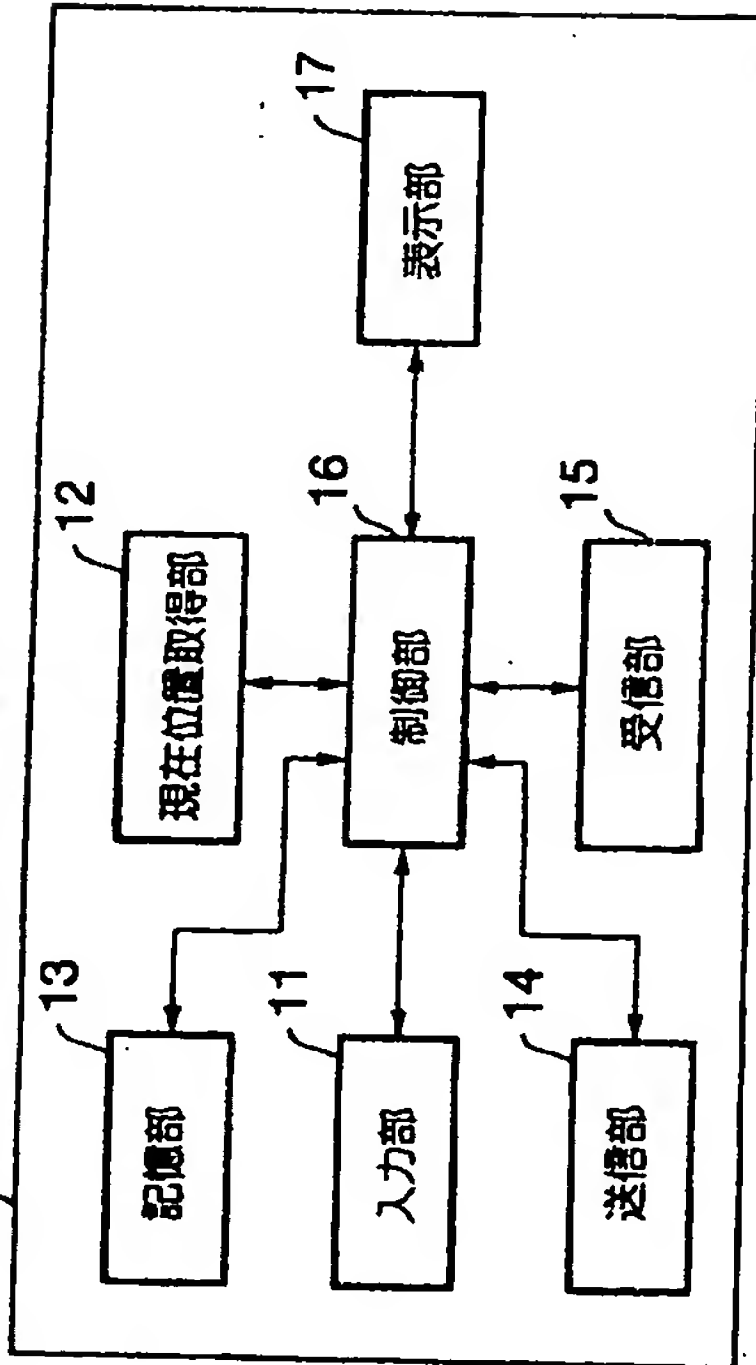


FIG. 1

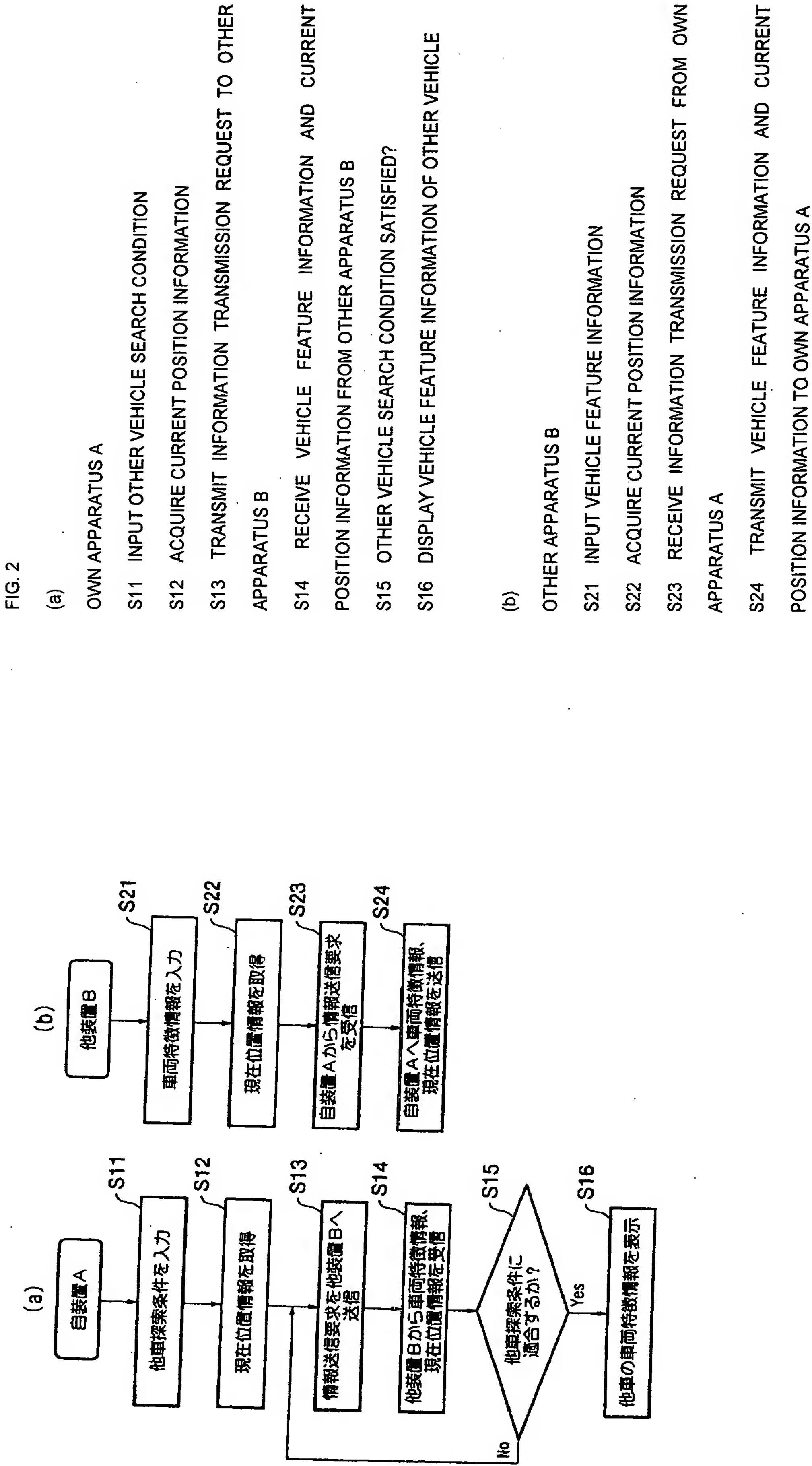
A OWN VEHICLE NAVIGATION APPARATUS

- 11 INPUT SECTION
- 12 CURRENT POSITION ACQUISITION SECTION
- 13 STORAGE SECTION
- 14 TRANSMISSION SECTION
- 15 RECEPTION SECTION
- 16 CONTROL SECTION
- 17 DISPLAY SECTION

B OTHER VEHICLE NAVIGATION APPARATUS

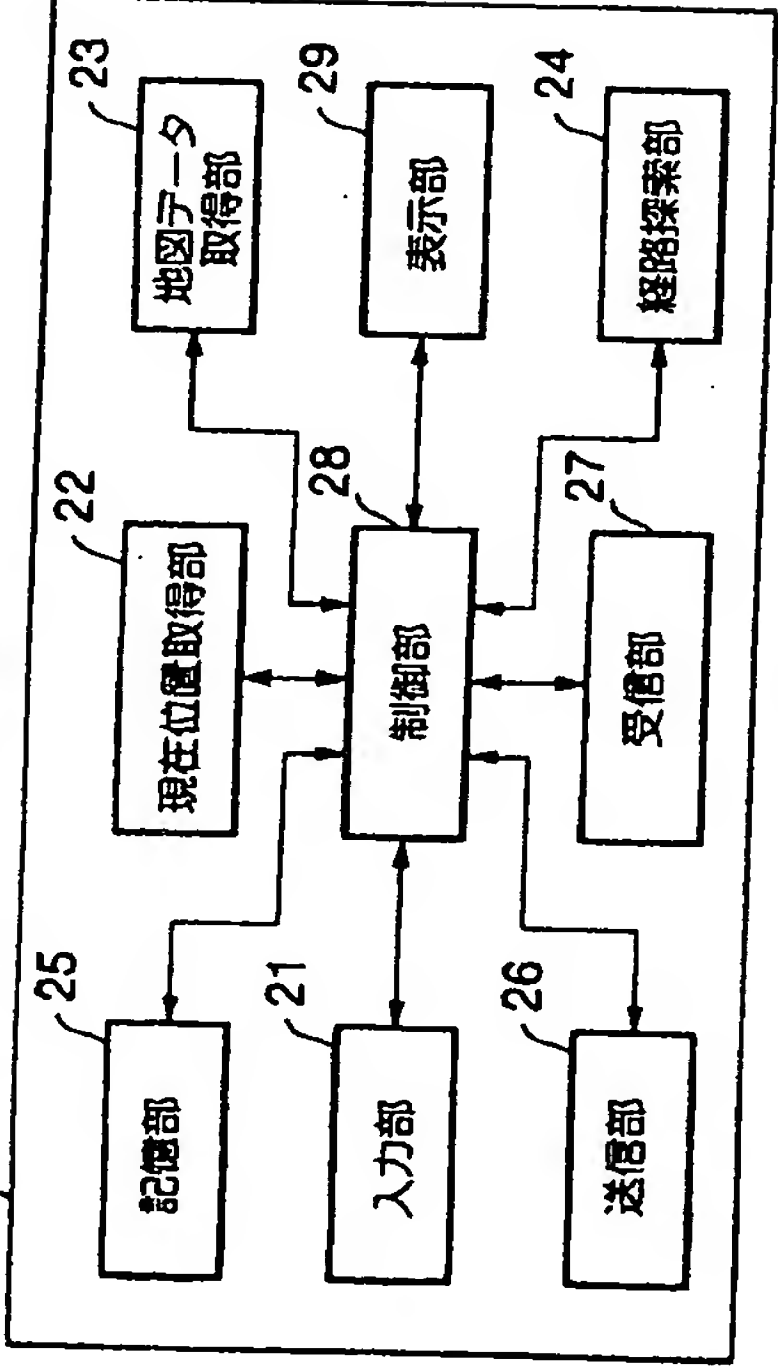
- 11 INPUT SECTION
- 12 CURRENT POSITION ACQUISITION SECTION
- 13 STORAGE SECTION
- 14 TRANSMISSION SECTION
- 15 RECEPTION SECTION
- 16 CONTROL SECTION
- 17 DISPLAY SECTION

[図2]



[図3]

A 自車側ナビゲーション装置



B 他車側ナビゲーション装置

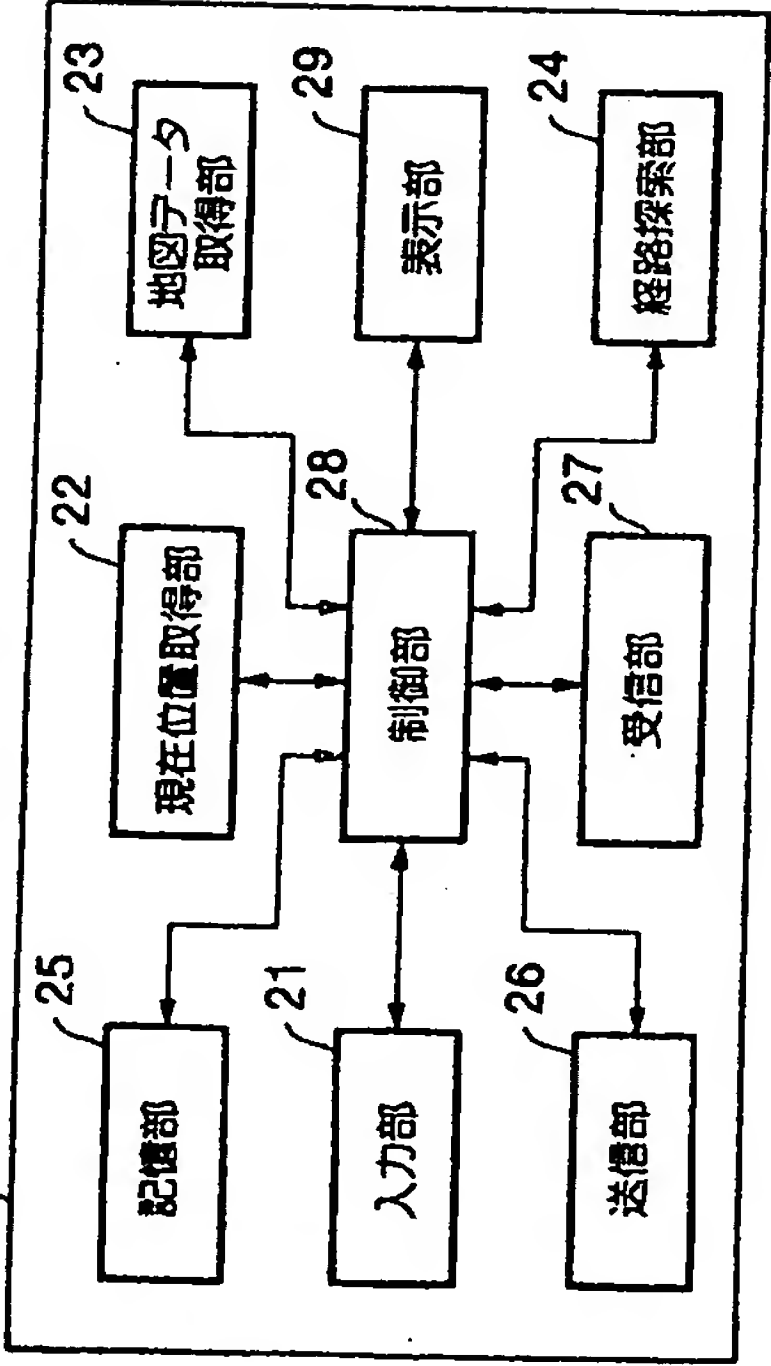


FIG. 3

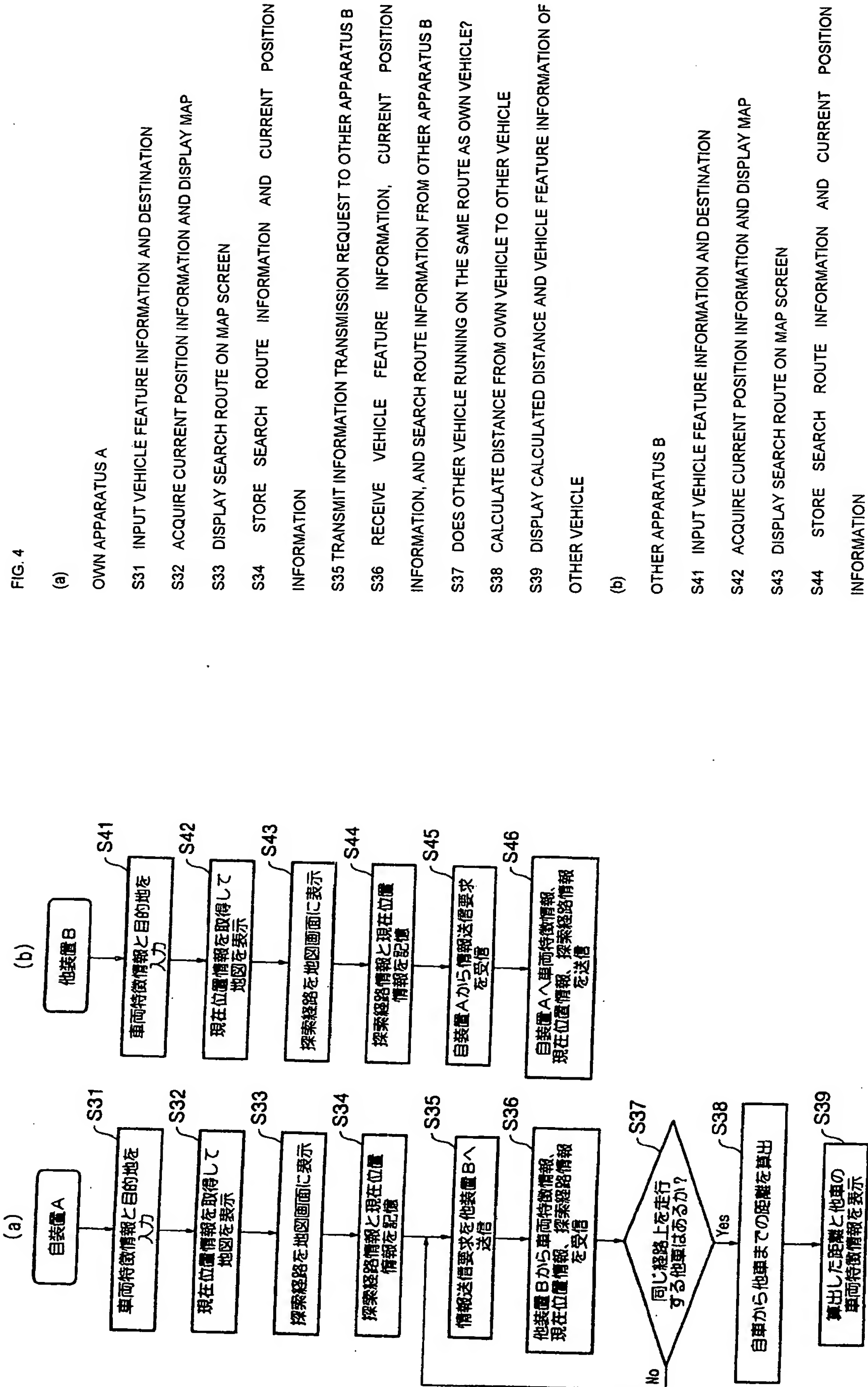
A OWN VEHICLE NAVIGATION APPARATUS

- 21 INPUT SECTION
- 22 CURRENT POSITION ACQUISITION SECTION
- 23 MAP DATA ACQUISITION SECTION
- 24 ROUTE SEARCH SECTION
- 25 STORAGE SECTION
- 26 TRANSMISSION SECTION
- 27 RECEPTION SECTION
- 28 CONTROL SECTION
- 29 DISPLAY SECTION

B OTHER VEHICLE NAVIGATION APPARATUS

- 21 INPUT SECTION
- 22 CURRENT POSITION ACQUISITION SECTION
- 23 MAP DATA ACQUISITION SECTION
- 24 ROUTE SEARCH SECTION
- 25 STORAGE SECTION
- 26 TRANSMISSION SECTION
- 27 RECEPTION SECTION
- 28 CONTROL SECTION
- 29 DISPLAY SECTION

[図4]



[図5]

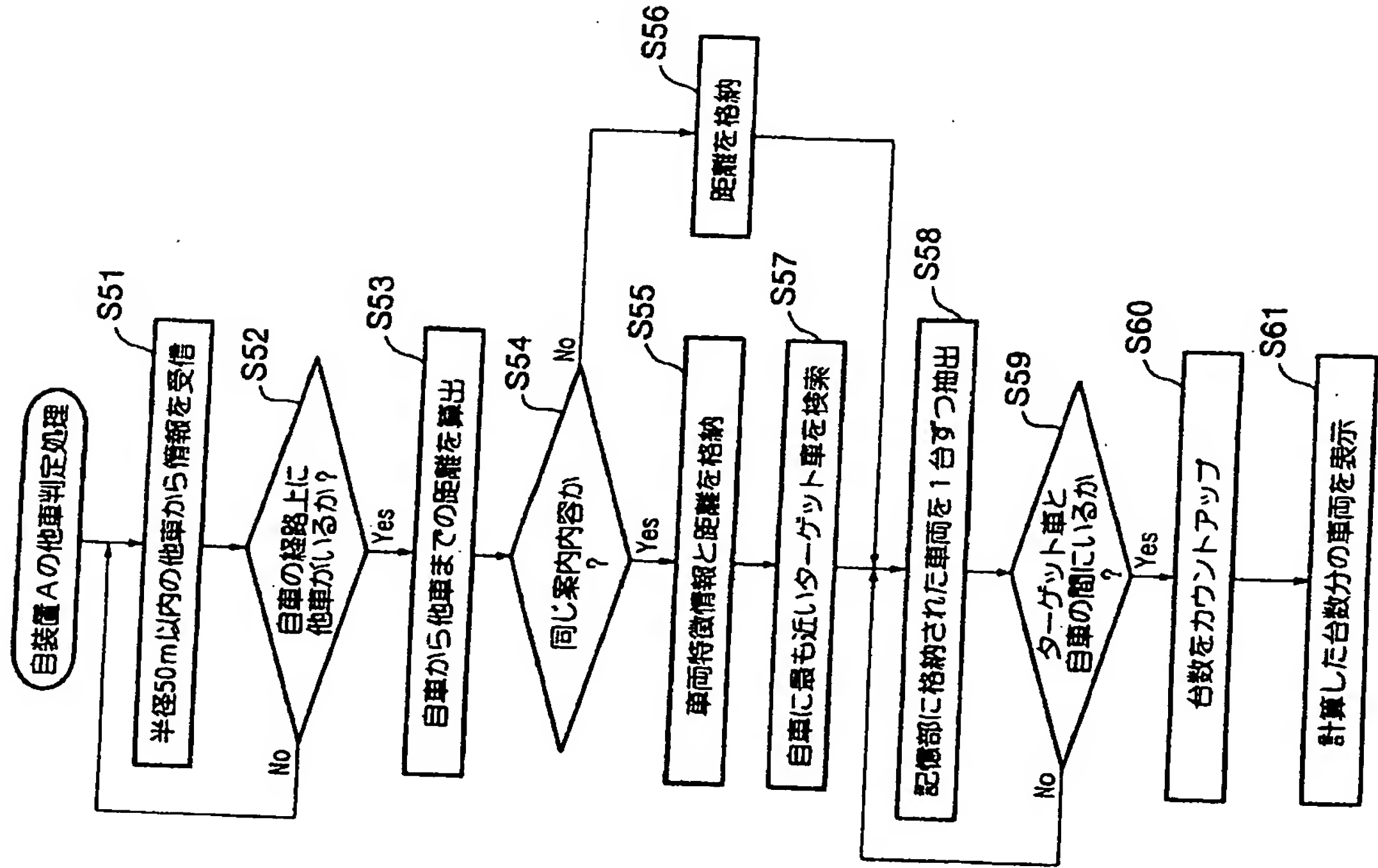


FIG. 5

OTHER VEHICLE DETERMINATION PROCESSING OF OWN APPARATUS A

S51 RECEIVE INFORMATION FROM OTHER VEHICLE WITHIN RADIUS OF 50m

S52 DOES OTHER VEHICLE EXIST ON ROUTE OF OWN VEHICLE?

S53 CALCULATE DISTANCE FROM OWN VEHICLE TO OTHER VEHICLE

S54 SAME GUIDANCE DESCRIPTION?

S55 STORE VEHICLE FEATURE INFORMATION AND DISTANCE

S56 STORE DISTANCE

S57 SEARCH FOR TARGET VEHICLE NEAREST TO OWN VEHICLE

S58 EXTRACT VEHICLES STORED IN STORAGE SECTION ONE AT A TIME

S59 DOES VEHICLE EXIST BETWEEN TARGET VEHICLE AND OWN VEHICLE?

S60 COUNT NUMBER OF VEHICLES

S61 DISPLAY AS MANY VEHICLES AS CALCULATED NUMBER OF VEHICLES